# The only UGV with aunav.NEO HD variable geometry

aunav.NEO HD is the only Unmanned Ground Vehicle (UGV) with explosives disposal capabilities (EOD/IEDD), HazMat CBRN(e) handling, as well as logistics (mule), medical support (MEDEVAC) and reconnaissance (Recce) with a variable geometry system. It can automatically increase or decrease its width in mere seconds.



## **ONE ROBOT FITS ALL**

- · Variable geometry system<sup>1</sup>: the UGV automatically increases or decreases its width to optimize its mobility and stability depending on whether it's in narrow or wide spaces.
- Platform self-stabilization: the self-stabilization system always keeps the UGV platform in a horizontal position on stairs, ramps, slopes or uneven debris-filled terrain.
- Plug & play payload technology: self-detection and real-time configuration of any accessory, without the need for operator intervention.
- **Demountable:** its main arm, flippers and batteries can easily be uncoupled from the UGV without using special tools, making it easy to transport in any vehicle.
- Strength and power: allows the operator to manipulate and move objects of up to 80 kg easily and skillfully.
- Autonomous capacities: autonomous indoor and outdoor navigation systems that generate 3D maps of the environment.

<sup>1</sup>Patented.

#### MAIN FEATURES

Stowed length (recommended- v	vidth & flippers) 880 mm (34.6")
Stowed width (recommended- w	idth & flippers) 605 mm (23.6")
Stowed height (recommended- v	vidth & flippers) 840 mm (33")
Traction system	4 flippers with independent
	or coordinated movement
Maximum speed	5 km/h (3.1 mph)
Slopes & stairs	45° (depending on surface)
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Horizontal platform	Automatically keeps the
& stable centre of gravity	platform as horizontal as
	possible or maintains the
	centre of gravity within
	the area of the base of
	the platform
Variable geometry	The UGV can dynamically
variable geometry	change its width from
	400 mm (15.7") to
	680 mm (26.8") to adapt to
	the required situation
Platform roll and pitch	Yes
"doggy" movement	
Anti-overturn system	Yes
Obstacle collision avoidance	e system Yes
Directional two-way audio sy	vstem Yes
Materials	Structure of aeronautical
Matchais	aluminium alloy and high
	resistance steel alloy
	Plastic and UV
	technical composites
Typical operating time	Aprox. 5 h
	(depending on task)
Power system	Military / Standard
-	rechargeable lithium-ion
	batteries (BB-2590/U)
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#### **ARM FEATURES**

Type of arm	Electric arm
Degrees of Freedom (DoF)	7°
Base turret rotation	360°
Gripper rotation	360° endless
Maximum vertical reach	2,780 mm (109.4'')
(from ground level)	
Maximum horizontal reach	1,800 mm (70.9")
(from platform front side)	
Maximum reach	- 1,167 mm (45.9'')
below ground level	
Maximum lift capacity	80 kg
Load weighing sensor	Yes
Arm to platform and ground	Yes
collision avoidance system	
Gripper based	Yes
"snake" movement	
Turret based	Yes
"snake" movement	
Self-calibration	Yes

### **VISION AND LIGHTING SYSTEM**

Standard	Front and rear driving vision kit with EO/IR camera, dimmable LED/IR lighting system and 2 distance sensors each PTZ mast vision kit with EO/IR camera and dimmable IR lighting system End-effector vision kit with EO/IR camera, dimmable LED/IR/UV lighting system and 1 distance sensor
Options	Maximum 19 cameras (inc. standard configuration): Platform side vision kit with 1 left and 1 right driving vision module with EO/IR camera, dimmable LED/IR/UV lighting system and 2 distance sensors each Accessory and additional views vision kit with EO/IR camera, dimmable LED/IR/UV lighting system and adjustable support Vision module with zoom camera with EO/IR camera and dimmable IR lighting system Thermal cameras 360° cameras UV cameras High-speed cameras

#### **DEFUSING EQUIPMENT**

Disruptors	Double disruptor mounting plate with fail-safe firing circuit, disruptor vision module with EO/IR camera, dimming LED/IR/UV lighting system, 2 distance sensors, and laser pointer
Firing cable reel Shotgun	Yes, with fall-safe firing, 100m Shotgun mounting plate with fail-safe firing circuit shotgun vision module with EO/IR camera, dimming IR/LED/UV lighting system, 1 distance sensor, and laser pointer

The technical characteristics and equipment depend on the configuration and version of the robot. Equipment includes options. All the data is accurate, with the exception of possible typographical errors. All photos are the propriety of aunav or their use has been authorised by their respective owners.

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### MANIPULATORS

Parallel gripper with	Yes
pressure sensor	
Gripper fitted tools (BATS)	Yes

#### **AUTOMATIC TOOLS**

Number of simultaneous tools	Two
Recoilless disruptor mount tool	Yes
MN-MIMO Relay radio	Yes

## NAVIGATION

Out of range	When the UGV loses
	comms link with the OCU, it
	automatically returns to the
	point where it recovers it
Go back 15 m	The UGV autonomously
	goes in reverse for 15 m to
	get out of a narrow space
Follow-me	The UGV follows an object
	or person in front of it
Reverse mode	UGV in reverse with
	the controls as if it were
	in forward driving
Indoor / Outdoor navigation	Yes / Yes
GPS / Galileo / Glonass / Be	eidou Yes

#### **OPERATOR CONTROL UNIT (OCU)** aunav.ROCS

Operation	Integrated joysticks navigation and switches
Typical operating time	Aprox. 5 h (depending on task)
Videofeeds	Up to 8 video feed simultaneously in HD
Videorecording	Yes
Screenshots	Yes
Blackout mode	Yes
3D Avatar	Yes
Power system	Rechargeable lithium-ion batteries
Communications system	MN-MIMO COFDM radio, Fibre Optic, Ethernet

## **DETECTION SYSTEMS**

X-Ray system	Several X-ray systems
	integrated
CBRN	Any under demand